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# Computer graphics III – Low-discrepancy sequences and quasi-Monte Carlo methods

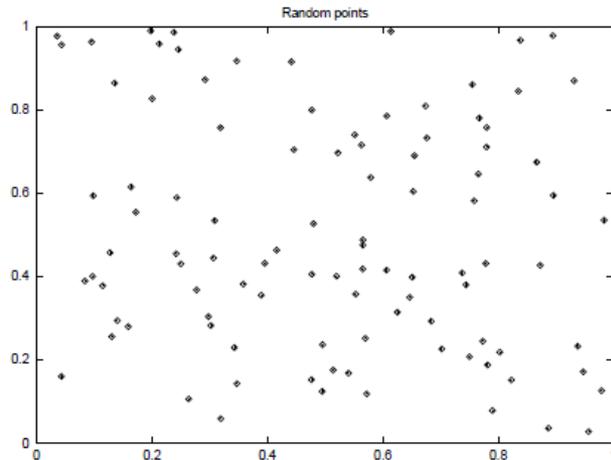
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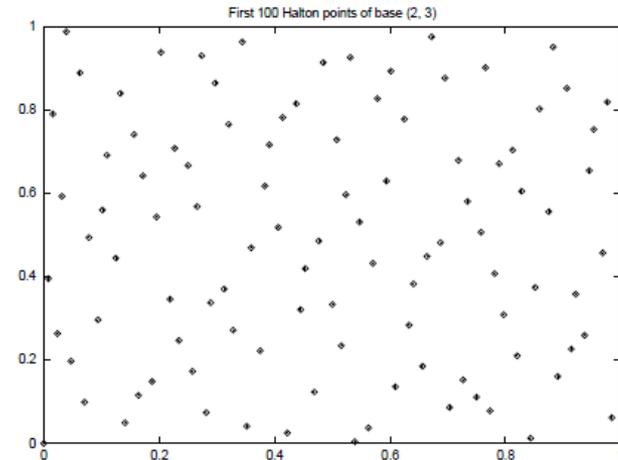
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# Quasi-Monte Carlo

- Goal: Use point sequences that cover the integration domain as uniformly as possible, while keeping a ‘randomized’ look of the point set

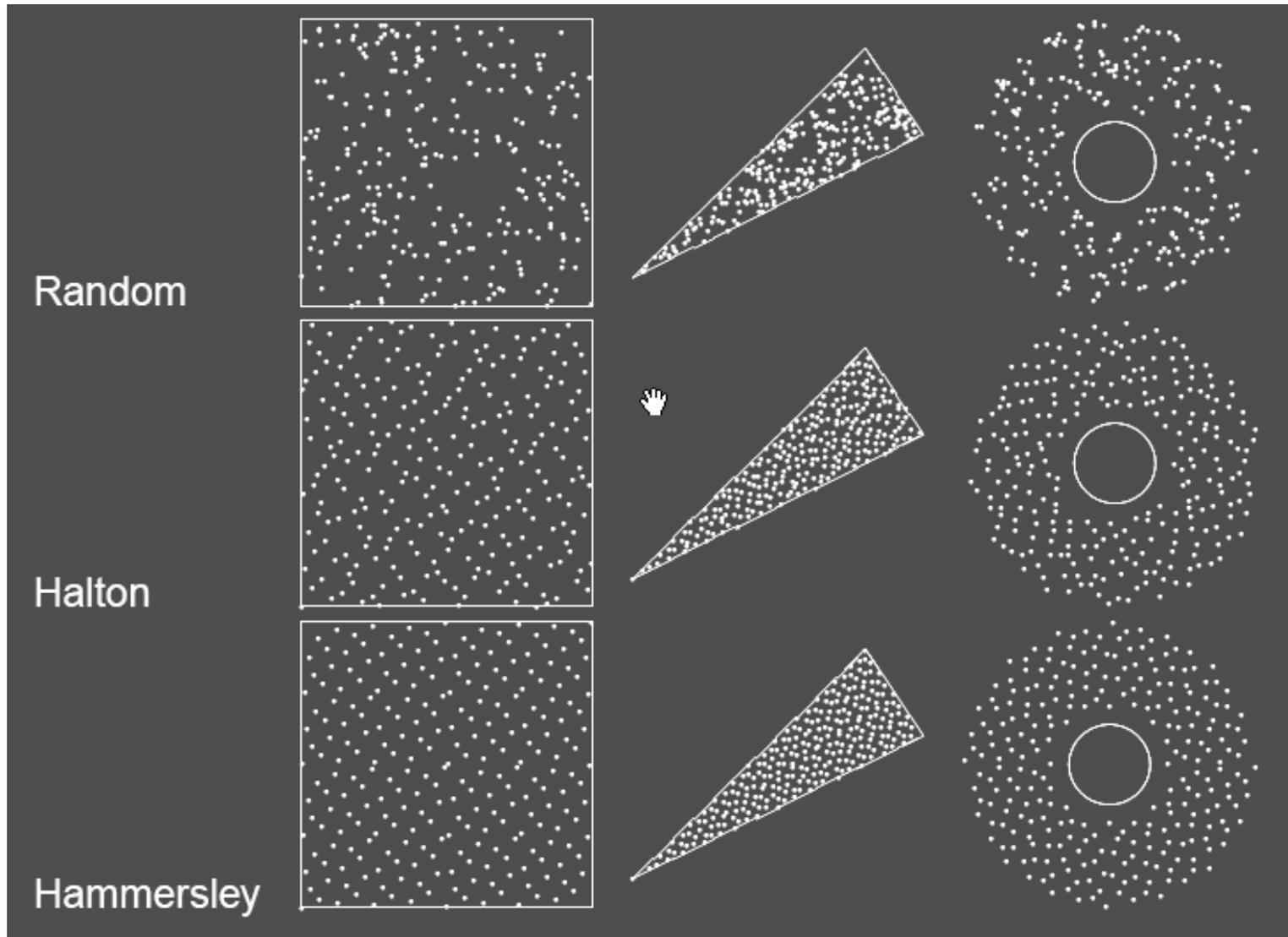


High Discrepancy  
(clusters of points)



Low Discrepancy  
(more uniform)

# Transformation of point sets



# MC vs. QMC

Monte Carlo  
(230s)



padded  
Hammersley  
(202s)



# Quasi Monte Carlo (QMC) methods

- Use of strictly deterministic sequences instead of random numbers
- All formulas as in MC, just the underlying proofs cannot rely on the probability theory (nothing is random)
- Based on sequences **low-discrepancy sequences**

# Defining discrepancy

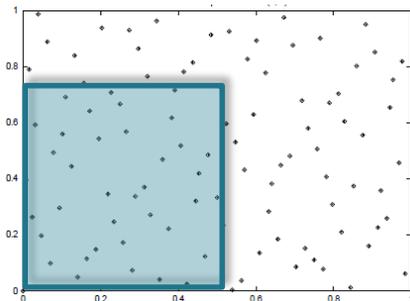
- $s$ -dimensional “brick” function:

$$\mathcal{L}(\mathbf{z}) = \begin{cases} 1 & \text{if } 0 \leq \mathbf{z}|_1 \leq v_1, 0 \leq \mathbf{z}|_2 \leq v_2, \dots, 0 \leq \mathbf{z}|_s \leq v_s \\ 0 & \text{otherwise.} \end{cases}$$

- True volume of the “brick” function:

$$V(A) = \prod_{j=1}^s v_j$$

- MC estimate of the volume of the “brick”:



$$\frac{1}{N} \sum_{i=1}^N f(\mathbf{z}_i) = \frac{m(A)}{N}$$

total number of sample points

number of sample points that actually fell inside the “brick”

# Discrepancy

- Discrepancy (of a point sequence) is the maximum possible error of the MC quadrature of the “brick” function over all possible brick shapes:

$$\mathcal{D}^*(\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_N) = \sup_A \left| \frac{m(A)}{N} - V(A) \right|$$

- serves as a measure of the uniformity of a point set
- must converge to zero as  $N \rightarrow \infty$
- the lower the better (cf. **Koksma-Hlawka Inequality**)

# Koksma-Hlawka inequality

- Koksma-Hlawka inequality

„variation“ of  $f$

$$\left| \int_{\mathbf{z} \in [0,1]^s} f(\mathbf{z}) \, d\mathbf{z} - \frac{1}{N} \sum_{i=1}^N f(\mathbf{z}_i) \right| \leq \mathcal{V}_{\text{HK}} \cdot \mathcal{D}^*(\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_N)$$

- ❑ the KH inequality only applies to  $f$  with finite variation
- ❑ QMC can still be applied even if the variation of  $f$  is infinite

# Van der Corput Sequence (base 2)

$i$	binary form of $i$	radical inverse	$H_i$
1	1	0.1	0.5
2	10	0.01	0.25
3	11	0.11	0.75
4	100	0.001	0.125
5	101	0.101	0.625
6	110	0.011	0.375
7	111	0.111	0.875

- point placed in the middle of the interval
- then the interval is divided in half
- has low-discrepancy

# Van der Corput Sequence

- **b ... Base**
- radical inverse

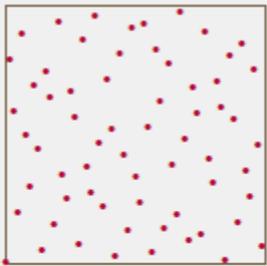
$$i = \sum_{j=0}^{\infty} a_j(i) b^j \quad \mapsto \quad \Phi_b(i) := \sum_{j=0}^{\infty} a_j(i) b^{-j-1}$$

# Van der Corput Sequence (base $b$ )

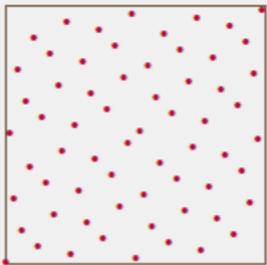
```
double radicalInverse(const int base, int i)
{
    double digit, radical;
    digit = radical = 1.0 / (double)base;
    double inverse = 0.0;
    while(i)
    {
        inverse += digit * (double)(i % base);
        digit *= radical;
        i /= base;
    }
    return inverse;
}
```

# Sequences in higher dimension

Halton sequence  $x_i := (\Phi_{b_1}(i), \dots, \Phi_{b_s}(i))$  where  $b_i$  is the  $i$ -th prime number



Hammersley point set  $x_i := \left( \frac{i}{n}, \Phi_{b_1}(i), \dots, \Phi_{b_{s-1}}(i) \right)$



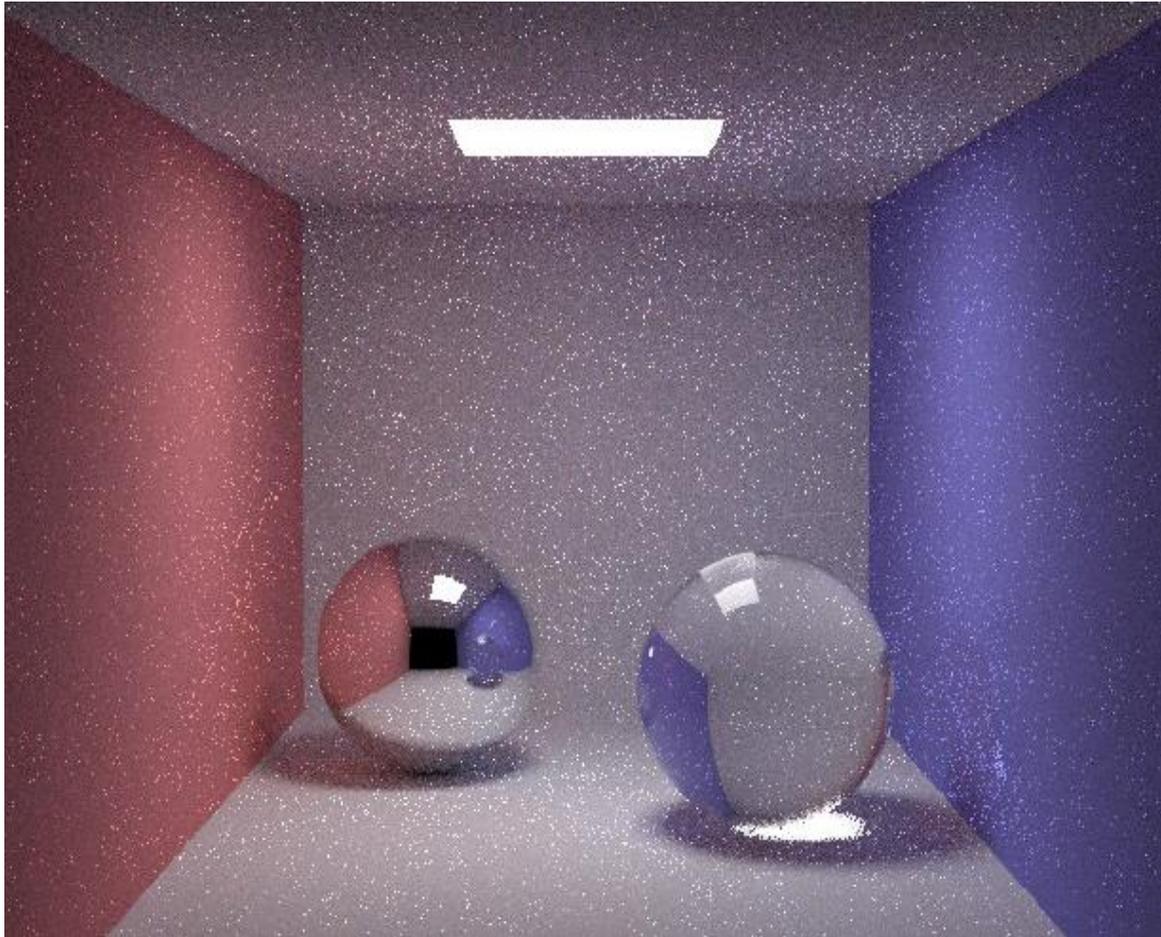
# Use in path tracing

- **Objective:** Generated paths should cover the entire high-dimensional path space uniformly
- **Approach:**
  - Paths are interpreted as “points” in a high-dimensional path space
  - Each path is defined by a long vector of “random numbers”
    - **Subsequent random events** along a single path use **subsequent components** of the **same** vector
  - Only when tracing the next path, we switch to a brand new “random vector” (e.g. next vector from a Halton sequence)

# Quasi-Monte Carlo (QMC) Methods

- Disadvantages of QMC:
  - Regular patterns can appear in the images (instead of the more acceptable noise in purely random MC)
  - Random scrambling can be used to suppress it

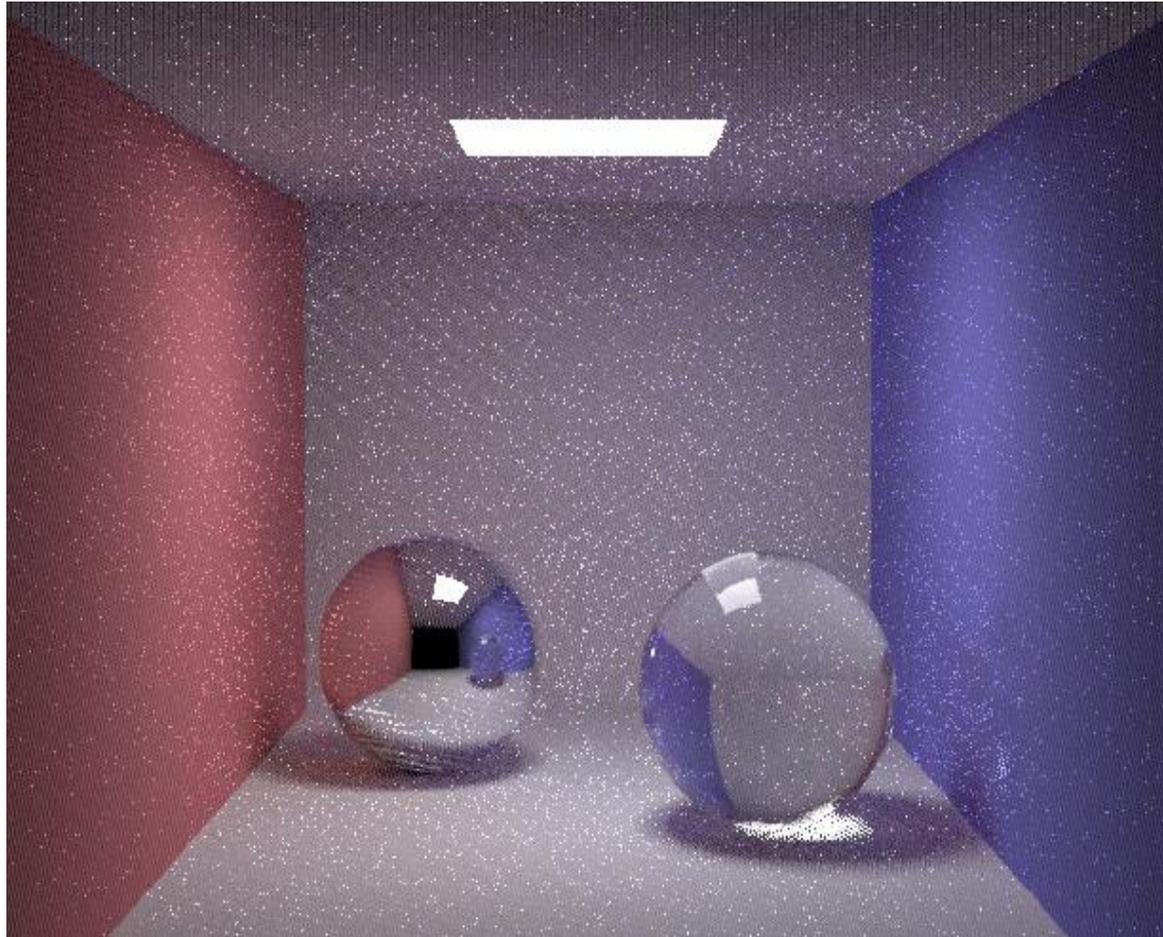
# Stratified sampling



Henrik Wann Jensen

10 paths per pixel

# Quasi-Monte Carlo



Henrik Wann Jensen

10 paths per pixel

# Fixní náhodná sekvence



Henrik Wann Jensen

10 paths per pixel